

HEF4585B

4-bit magnitude comparator

Rev. 6 — 21 November 2011

Product data sheet

1. General description

The HEF4585B is a 4-bit magnitude comparator that compares two 4-bit words, A and B, and determines whether A is greater than B, A is equal to B, or A is less than B. Each word has four parallel inputs (A0 to A3 and B0 to B3) with A3 and B3 being the most significant inputs. Three outputs are provided: A greater than B (QA>B), A less than B (QA<B) and A equal to B (QA=B). Three expander inputs (IA>B, IA<B, and IA=B) allow cascading of the devices, to compare 8, 12, 16, ..., bits without external gates.

To operate a single device or a device in the least significant position in a cascaded chain, the expander inputs are connected as follows: IA=B = IA>B = HIGH and IA<B = LOW. All other cascaded devices have IA=B and IA<B connected to QA=B and QA<B respectively of the previous (less significant) device in the chain, while input IA>B is connected to a HIGH (see [Figure 6](#)). Operation is not restricted to pure binary code; the devices will work with any monotonic code. [Table 3](#) describes the operation of the device under all possible logic conditions.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$
- Complies with JEDEC standard JESD 13-B

3. Ordering information

Table 1. Ordering information

All types operate from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$

| Type number | Package | | Version |
|-------------|---------|--|----------|
| | Name | Description | |
| HEF4585BP | DIP16 | plastic dual in-line package; 16 leads (300 mil) | SOT38-4 |
| HEF4585BT | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |



4. Functional diagram

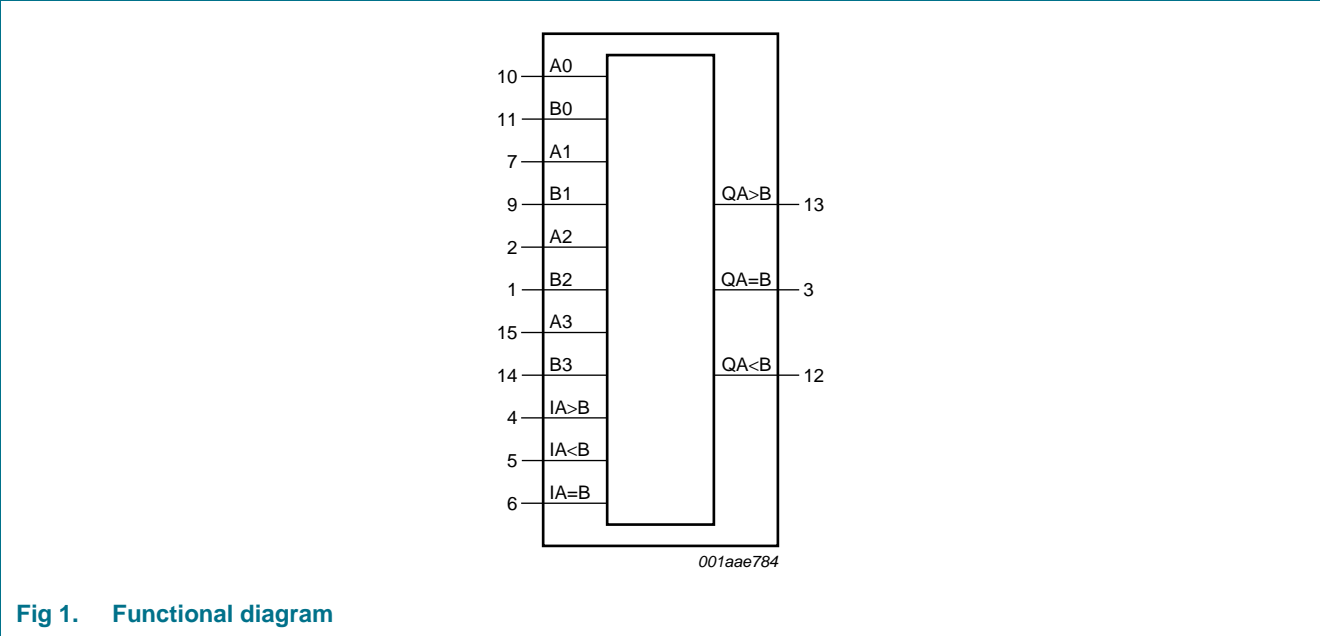


Fig 1. Functional diagram

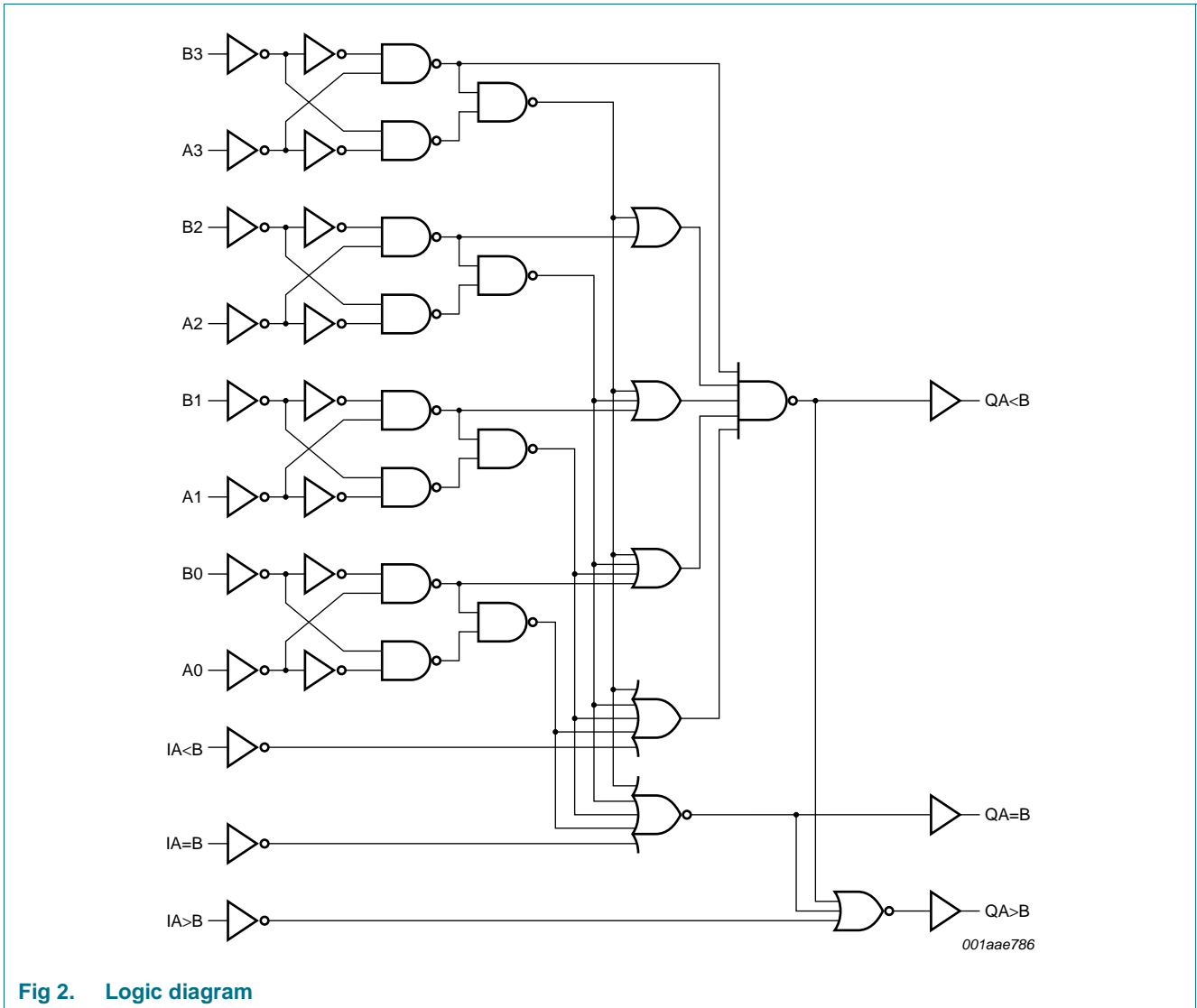
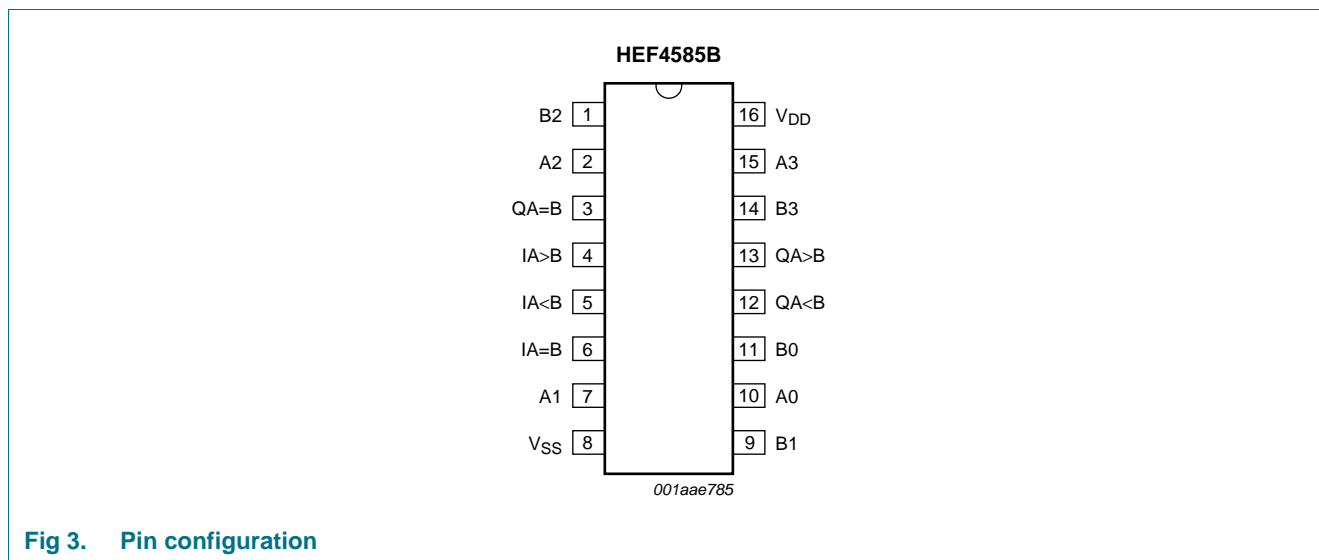


Fig 2. Logic diagram

5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|--------------|-------------------------|
| A[0:3] | 10, 7, 2, 15 | word A parallel input |
| B[0:3] | 11, 9, 1, 14 | word B parallel input |
| IA>B | 4 | expander input |
| IA=B | 6 | expander input |
| IA<B | 5 | expander input |
| QA>B | 13 | A greater than B output |
| QA=B | 3 | A equal to B output |
| QA<B | 12 | A less than B output |
| V _{DD} | 16 | supply voltage |
| V _{SS} | 8 | ground supply voltage |

6. Functional description

Table 3. Function selection [1]

| Comparing inputs | | | | Cascading inputs | | | Outputs | | | |
|------------------|---------|---------|---------|------------------|------|------|---------|------|------|---|
| A3, B3 | A2, B2 | A1, B1 | A0, B0 | IA>B | IA<B | IA=B | QA>B | QA<B | QA=B | |
| A3 > B3 | X | X | X | H | X | X | H | L | L | |
| A3 < B3 | X | X | X | X | X | X | L | H | L | |
| A3 = B3 | A2 > B2 | X | X | H | X | X | H | L | L | |
| | A2 < B2 | X | X | X | X | X | L | H | L | |
| | A2 = B2 | A1 > B1 | X | X | H | X | X | H | L | L |
| | | A1 < B1 | X | X | X | X | X | L | H | L |
| | | A1 = B1 | A0 > B0 | X | X | H | X | X | H | L |
| | A0 < B0 | | X | X | X | X | X | L | H | L |
| | A0 = B0 | | X | X | X | X | X | L | H | L |
| | | | | H | L | L | H | L | L | |
| | | | | X | H | L | L | H | L | |
| | | | | [2] | | | | | | |
| | | | | X | H | H | L | H | H | |
| | | | | L | L | L | L | L | L | |

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care.

[2] The first 11 lines describe the normal operation under all conditions that will occur in a single device or in a serial expansion scheme. The last 2 lines describe the operation under abnormal conditions on the cascading inputs. These conditions occur when the parallel expansion technique is used.

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|-------------------------|---|------|-----------------------|------|
| V _{DD} | supply voltage | | -0.5 | +18 | V |
| I _{IK} | input clamping current | V _I < -0.5 V or V _I > V _{DD} + 0.5 V | - | ±10 | mA |
| V _I | input voltage | | -0.5 | V _{DD} + 0.5 | V |
| I _{OK} | output clamping current | V _O < -0.5 V or V _O > V _{DD} + 0.5 V | - | ±10 | mA |
| I _{I/O} | input/output current | | - | ±10 | mA |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| T _{amb} | ambient temperature | | -40 | +85 | °C |
| P _{tot} | total power dissipation | DIP16 package | [1] | 750 | mW |
| | | SO16 package | [2] | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 °C.

[2] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|-----|----------|-----------------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +85 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5\text{ V}$ | - | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10\text{ V}$ | - | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15\text{ V}$ | - | - | 0.08 | $\mu\text{s/V}$ |

9. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ °C}$ | | $T_{amb} = 25\text{ °C}$ | | $T_{amb} = 85\text{ °C}$ | | Unit |
|----------|---------------------------|--------------------------|----------|---------------------------|-----------|--------------------------|-----------|--------------------------|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | $I_O = 0\text{ A}$ | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C_I | input capacitance | | - | - | - | - | 7.5 | - | - | pF |

10. Dynamic characteristics

Table 7. Dynamic characteristics

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ °C}$; for test circuit see [Figure 5](#) unless otherwise specified.

| Symbol | Parameter | Conditions ^{[1][2]} | V _{DD} | Extrapolation formula ^[3] | Min | Typ | Max | Unit |
|------------------|-------------------------------|--|-----------------|--------------------------------------|-----|-----|-----|------|
| t _{PHL} | HIGH to LOW propagation delay | An, Bn to Qn; see Figure 4 | 5 V | 133 ns + (0.55 ns/pF)C _L | - | 160 | 320 | ns |
| | | | 10 V | 54 ns + (0.23 ns/pF)C _L | - | 65 | 130 | ns |
| | | | 15 V | 37 ns + (0.16 ns/pF)C _L | - | 45 | 90 | ns |
| | | In to Qn; see Figure 4 | 5 V | 83 ns + (0.55 ns/pF)C _L | - | 110 | 220 | ns |
| | | | 10 V | 34 ns + (0.23 ns/pF)C _L | - | 45 | 90 | ns |
| | | | 15 V | 22 ns + (0.16 ns/pF)C _L | - | 30 | 60 | ns |
| t _{PLH} | LOW to HIGH propagation delay | An, Bn to Qn; see Figure 4 | 5 V | 123 ns + (0.55 ns/pF)C _L | - | 150 | 300 | ns |
| | | | 10 V | 49 ns + (0.23 ns/pF)C _L | - | 60 | 120 | ns |
| | | | 15 V | 37 ns + (0.16 ns/pF)C _L | - | 45 | 90 | ns |
| | | In to Qn; see Figure 4 | 5 V | 93 ns + (0.55 ns/pF)C _L | - | 120 | 240 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF)C _L | - | 50 | 100 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF)C _L | - | 35 | 70 | ns |
| t _t | transition time | see Figure 4 | 5 V | 10 ns + (1.00 ns/pF)C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF)C _L | - | 20 | 40 | ns |

[1] Qn is QA>B, QA<B or QA=B

[2] In is IA>B, IA<B or IA=B

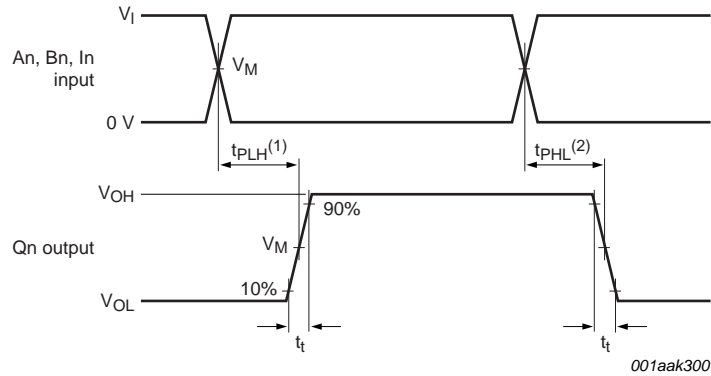
[3] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. $V_{SS} = 0\text{ V}$; $C_L = 50\text{ pF}$; $t_r = t_f \leq 20\text{ ns}$; $T_{amb} = 25\text{ °C}$.

| Symbol | Parameter | V _{DD} | Typical formula for P _D (μW) | where: |
|----------------|---------------------------|-----------------|---|--|
| P _D | dynamic power dissipation | 5 V | $P_D = 1250 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f _i = input frequency in MHz, |
| | | 10 V | $P_D = 5500 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f _o = output frequency in MHz, |
| | | 15 V | $P_D = 15000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | C _L = output load capacitance in pF, V _{DD} = supply voltage in V, Σ(f _o × C _L) = sum of the outputs. |

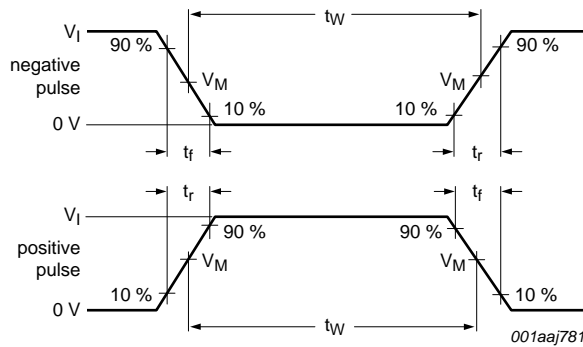
11. Waveforms



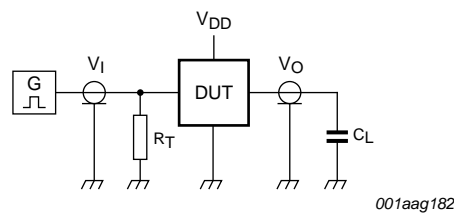
Measurement points shown in [Table 9](#)

- (1) Qn (QA>B, QA<B and QA=B) LOW to HIGH (t_{PLH}) transitions triggered by An, Bn or IA<B, IA>B and IA=B as shown by [Table 3](#).
- (2) Qn (QA>B, QA<B and QA=B) HIGH to LOW (t_{PHL}) transitions triggered by An, Bn or IA<B, IA>B and IA=B as shown by [Table 3](#).

Fig 4. Waveforms showing switching times



a. Input waveforms



b. Test circuit

Test data is given in [Table 9](#).

Definitions for test circuit:

DUT = Device Under Test

CL = Load capacitance including jig and probe capacitance;

RT = Termination resistance should be equal to output impedance Zo of the pulse generator.

Fig 5. Test circuit for measuring switching times

Table 9. Measurement points and test data

| Supply voltage | Input | | | Load |
|----------------|----------|----------|--------------|-------|
| | V_I | V_M | t_r, t_f | C_L |
| 5 V to 15 V | V_{DD} | $0.5V_I$ | ≤ 20 ns | 50 pF |

12. Application information

Some examples of applications for the HEF4585B are:

- Process controllers
- Servo-motor control

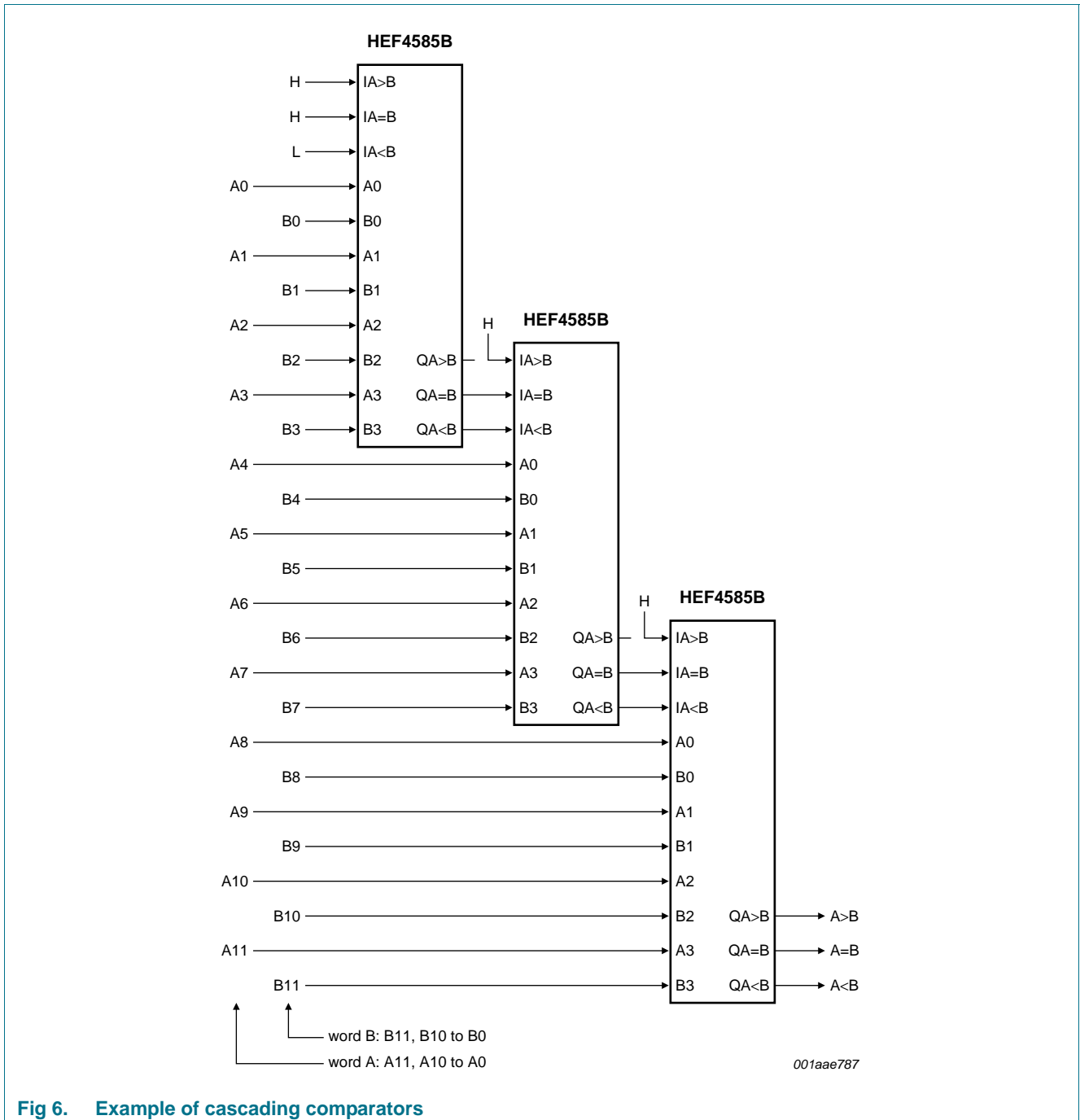


Fig 6. Example of cascading comparators

13. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4

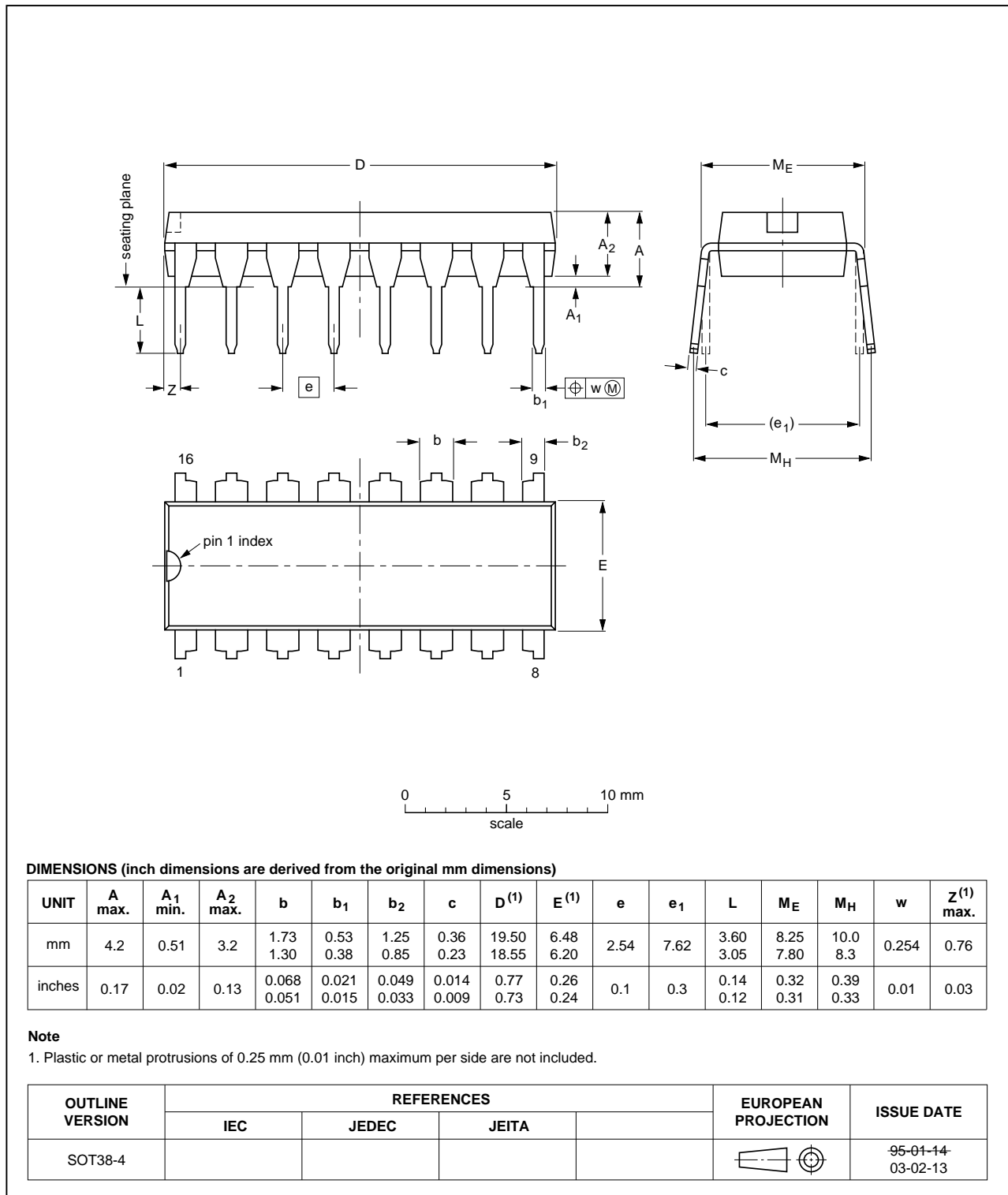


Fig 7. Package outline 38-4 (DIP16)

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

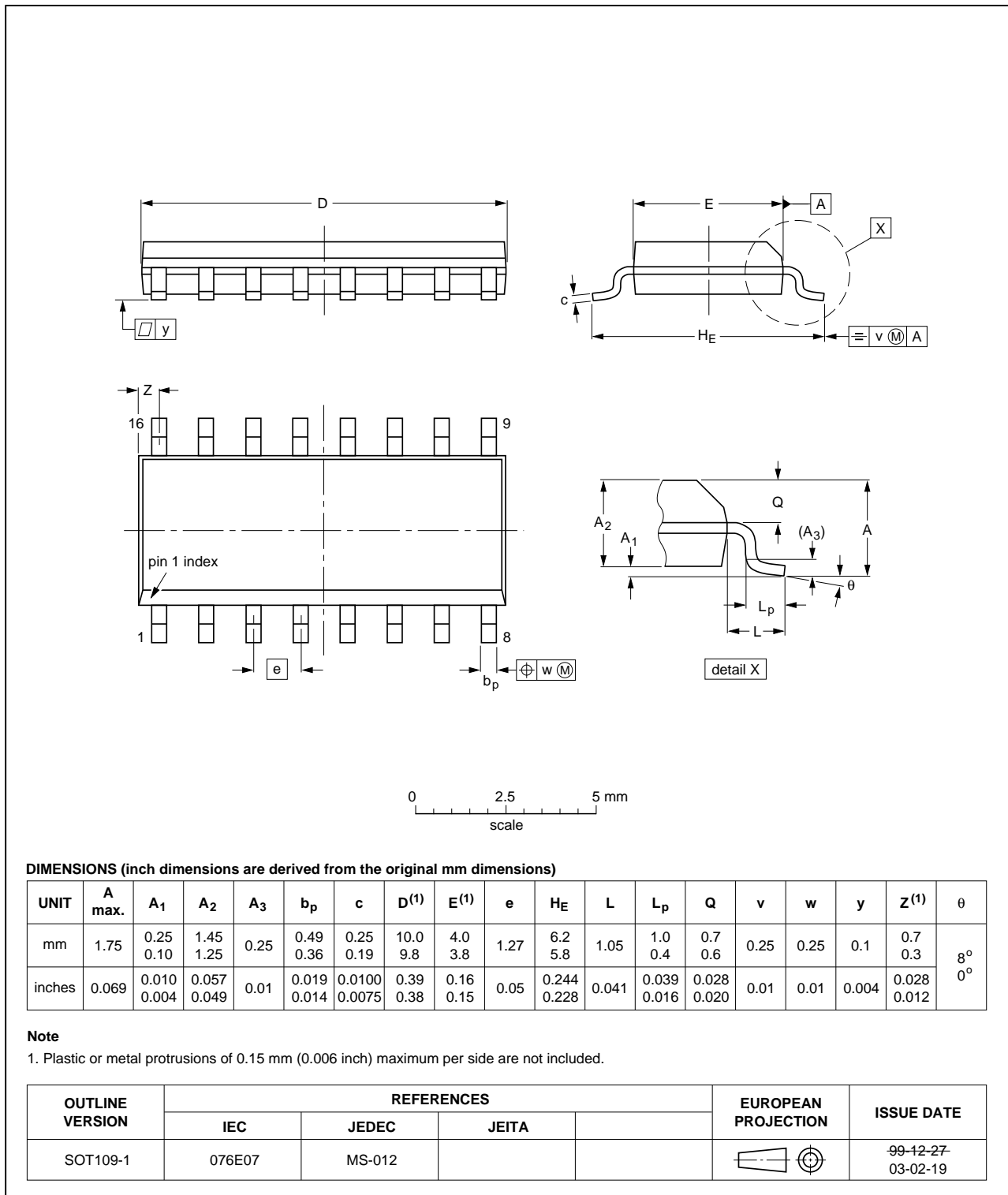


Fig 8. Package outline 109-1 (SO16)

14. Revision history

Table 10. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|------------------|--|-----------------------|---------------|------------------|
| HEF4585B v.6 | 20111121 | Product data sheet | - | HEF4585B v.5 |
| Modifications: | <ul style="list-style-type: none">• Section Applications removed• Table 6: I_{OH} minimum values changed to maximum | | | |
| HEF4585B v.5 | 20091222 | Product data sheet | - | HEF4585B v.4 |
| HEF4585B v.4 | 20090810 | Product data sheet | - | HEF4585B_CNV v.3 |
| HEF4585B_CNV v.3 | 19950101 | Product specification | - | HEF4585B_CNV v.2 |
| HEF4585B_CNV v.2 | 19950101 | Product specification | - | - |

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15.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
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[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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17. Contents

| | | |
|-----------|---|-----------|
| 1 | General description | 1 |
| 2 | Features and benefits | 1 |
| 3 | Ordering information | 1 |
| 4 | Functional diagram | 2 |
| 5 | Pinning information | 4 |
| 5.1 | Pinning | 4 |
| 5.2 | Pin description | 4 |
| 6 | Functional description | 5 |
| 7 | Limiting values | 5 |
| 8 | Recommended operating conditions | 6 |
| 9 | Static characteristics | 6 |
| 10 | Dynamic characteristics | 7 |
| 11 | Waveforms | 8 |
| 12 | Application information | 10 |
| 13 | Package outline | 11 |
| 14 | Revision history | 13 |
| 15 | Legal information | 14 |
| 15.1 | Data sheet status | 14 |
| 15.2 | Definitions | 14 |
| 15.3 | Disclaimers | 14 |
| 15.4 | Trademarks | 15 |
| 16 | Contact information | 15 |
| 17 | Contents | 16 |

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